

# MATH 226

## Notes on Assignment 10

### 3.3 Homogeneous Linear Systems with Constant Coefficients

#### Practice Problems: 1\*, 5\*, 6\*, 10\*, 15\*, 17, 18, 34

1. We look for eigenvalues and eigenvectors of

$$A = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix}.$$

We see that  $\det(A - \lambda I) = \lambda^2 - \lambda - 2 = (\lambda - 2)(\lambda + 1)$ . Therefore, the eigenvalues are given by  $\lambda = 2, -1$ . First,  $\lambda_1 = 2$  implies

$$A - \lambda_1 I = \begin{pmatrix} 1 & -2 \\ 2 & -4 \end{pmatrix}.$$

Therefore,

$$\mathbf{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_1$  and

$$\mathbf{x}_1(t) = e^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

is one solution of the system. Second,  $\lambda_2 = -1$  implies

$$A - \lambda_2 I = \begin{pmatrix} 4 & -2 \\ 2 & -1 \end{pmatrix}.$$

Therefore,

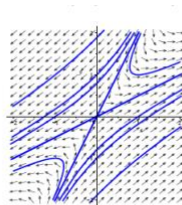
$$\mathbf{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_2$  and

$$\mathbf{x}_2(t) = e^{-t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

is a second solution of the system. Therefore, the general solution is given by

$$\mathbf{x}(t) = c_1 e^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$



If the initial condition is a multiple of  $\begin{pmatrix} 1 & 2 \end{pmatrix}^T$ , then the solution will tend to the origin along the eigenvector  $\begin{pmatrix} 1 & 2 \end{pmatrix}^T$ . Otherwise, the solution will grow, following the eigenvector  $\begin{pmatrix} 2 & 1 \end{pmatrix}^T$ .

5. We look for eigenvalues and eigenvectors of

$$A = \begin{pmatrix} 4 & -3 \\ 8 & -6 \end{pmatrix}.$$

We see that  $\det(A - \lambda I) = \lambda^2 + 2\lambda = \lambda(\lambda + 2)$ . Therefore, the eigenvalues are given by  $\lambda = 0, -2$ . First,  $\lambda_1 = 0$  implies

$$A - \lambda_1 I = \begin{pmatrix} 4 & -3 \\ 8 & -6 \end{pmatrix}.$$

Therefore,

$$\mathbf{v}_1 = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_1$  and

$$\mathbf{x}_1(t) = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

is one solution of the system. Second,  $\lambda_2 = -2$  implies

$$A - \lambda_2 I = \begin{pmatrix} 6 & -3 \\ 8 & -4 \end{pmatrix}.$$

Therefore,

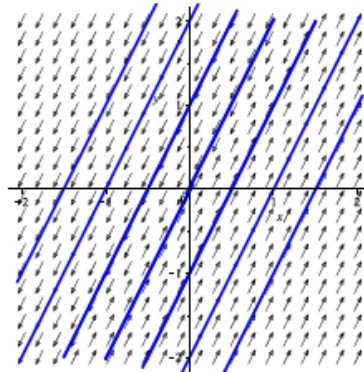
$$\mathbf{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_2$  and

$$\mathbf{x}_2(t) = e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

is a second solution of the system. Therefore, the general solution is given by

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 3 \\ 4 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$



Any solution starting at a point on the line of critical points remains fixed for all time at its starting point. A solution starting at any other point in the plane moves on a line parallel to  $\mathbf{v}_2$  toward the point of intersection of this line with the line of critical points.

6. We look for eigenvalues and eigenvectors of

$$A = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}.$$

We see that  $\det(A - \lambda I) = \lambda^2 + 4\lambda + 3 = (\lambda + 1)(\lambda + 3)$ . Therefore, the eigenvalues are given by  $\lambda = -1, -3$ . First,  $\lambda_1 = -1$  implies

$$A - \lambda_1 I = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}.$$

Therefore,

$$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_1$  and

$$\mathbf{x}_1(t) = e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

is one solution of the system. Second,  $\lambda_2 = -3$  implies

$$A - \lambda_2 I = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

Therefore,

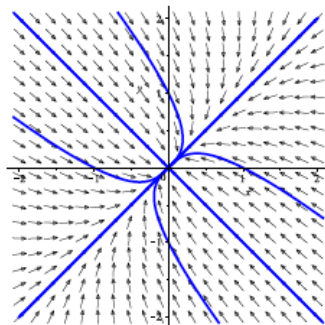
$$\mathbf{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_2$  and

$$\mathbf{x}_2(t) = e^{-3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

is a second solution of the system. Therefore, the general solution is given by

$$\mathbf{x}(t) = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$



If the initial condition is a multiple of  $\begin{pmatrix} 1 & -1 \end{pmatrix}^T$ , then the solution will tend to the origin along the eigenvector  $\begin{pmatrix} 1 & -1 \end{pmatrix}^T$ . Otherwise, the solution will tend to the origin, following the eigenvector  $\begin{pmatrix} 1 & 1 \end{pmatrix}^T$ .

10. We look for eigenvalues and eigenvectors of

$$A = \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix}.$$

We see that  $\det(A - \lambda I) = \lambda^2 - 6\lambda + 8 = (\lambda - 4)(\lambda - 2)$ . Therefore, the eigenvalues are given by  $\lambda = 4, 2$ . First,  $\lambda_1 = 4$  implies

$$A - \lambda_1 I = \begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix}.$$

Therefore,

$$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_1$  and

$$\mathbf{x}_1(t) = e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

is one solution of the system. Second,  $\lambda_2 = 2$  implies

$$A - \lambda_2 I = \begin{pmatrix} 3 & -1 \\ 3 & -1 \end{pmatrix}.$$

Therefore,

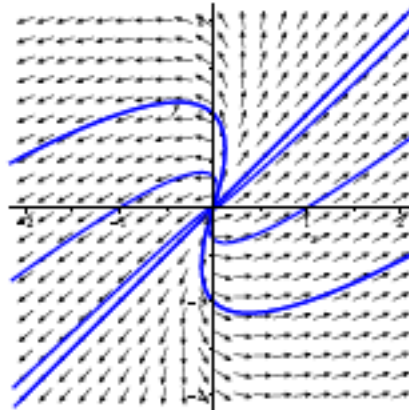
$$\mathbf{v}_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

is an eigenvector associated with  $\lambda_2$  and

$$\mathbf{x}_2(t) = e^{2t} \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

is a second solution of the system. Therefore, the general solution is given by

$$\mathbf{x}(t) = c_1 e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 3 \end{pmatrix}.$$



If the initial condition is a multiple of  $\begin{pmatrix} 1 & 3 \end{pmatrix}^T$ , then the solution will grow, staying on the eigenvector  $\begin{pmatrix} 1 & 3 \end{pmatrix}^T$ . Otherwise, the solution will grow, following the eigenvector  $\begin{pmatrix} 1 & 1 \end{pmatrix}^T$ .

15. From problem 10, the general solution is

$$\mathbf{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ 3 \end{pmatrix} + c_2 e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

The initial condition  $\mathbf{x}(0) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$  implies

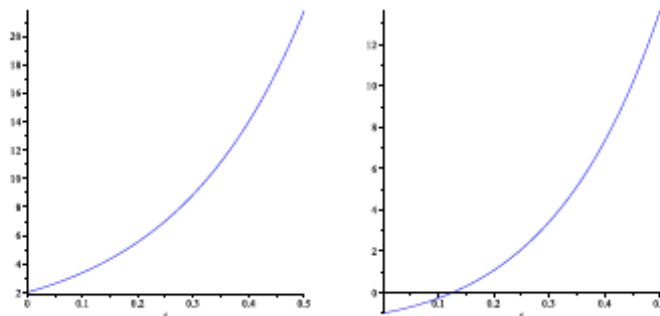
$$\begin{pmatrix} 1 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}.$$

Therefore,

$$\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 1 & -1 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \begin{pmatrix} -3/2 \\ 7/2 \end{pmatrix}.$$

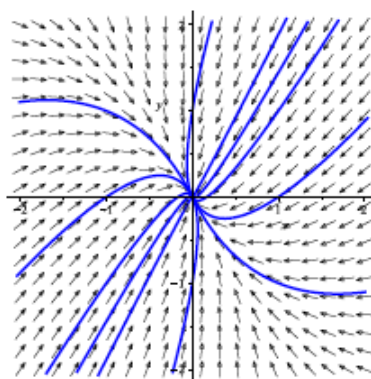
Therefore, the solution is

$$\mathbf{x}(t) = -\frac{3}{2} e^{2t} \begin{pmatrix} 1 \\ 3 \end{pmatrix} + \frac{7}{2} e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

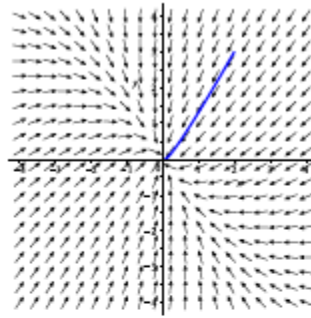


Both components tend to  $+\infty$  as  $t \rightarrow \infty$ .

17.(a)



(b)



(c) The general solution is given by

$$\mathbf{x}(t) = c_1 e^{-t} \begin{pmatrix} -1 \\ 2 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

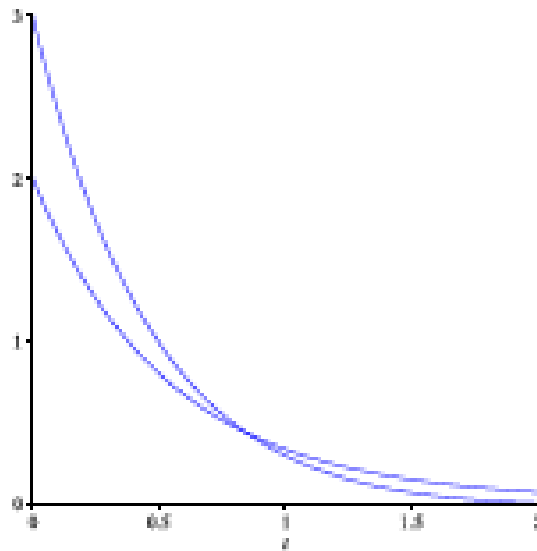
The initial condition  $\mathbf{x}(0) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$  implies

$$\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} -1/4 \\ 7/4 \end{pmatrix}.$$

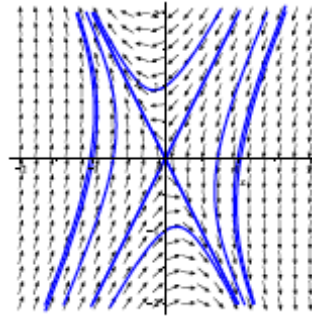
Therefore, the solution passing through the initial point  $(2, 3)$  is given by

$$\mathbf{x}(t) = -\frac{1}{4} e^{-t} \begin{pmatrix} -1 \\ 2 \end{pmatrix} + \frac{7}{4} e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

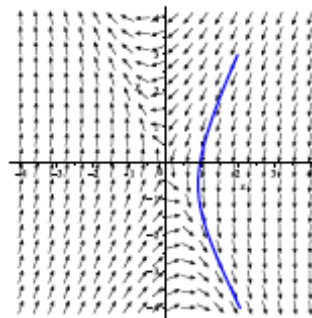
The component plots are shown below.



18.(a)



(b)



(c) The general solution is given by

$$\mathbf{x}(t) = c_1 e^t \begin{pmatrix} -1 \\ 2 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

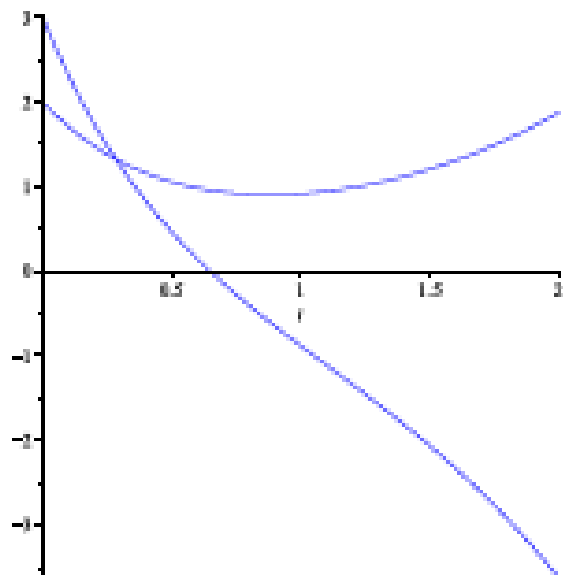
The initial condition  $\mathbf{x}(0) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$  implies

$$\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} -1/4 \\ 7/4 \end{pmatrix}.$$

Therefore, the solution passing through the initial point (2, 3) is given by

$$\mathbf{x}(t) = -\frac{1}{4} e^t \begin{pmatrix} -1 \\ 2 \end{pmatrix} + \frac{7}{4} e^{-2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

The component plots are shown below.



34.(a) For  $\alpha = 0.5$ , the characteristic equation is  $2\lambda^2 + 4\lambda + 1 = 0$ . Therefore, the eigenvalues are  $\lambda = -1 \pm 1/\sqrt{2}$ . The eigenvector corresponding to  $\lambda_1 = -1 + 1/\sqrt{2}$  is  $\mathbf{v}_1 = (-\sqrt{2} \ 1)^T$ . The eigenvector corresponding to  $\lambda_2 = -1 - 1/\sqrt{2}$  is  $\mathbf{v}_2 = (\sqrt{2} \ 1)^T$ . Therefore, the general solution is

$$\mathbf{x}(t) = c_1 e^{(-1+1/\sqrt{2})t} \begin{pmatrix} -\sqrt{2} \\ 1 \end{pmatrix} + c_2 e^{(-1-1/\sqrt{2})t} \begin{pmatrix} \sqrt{2} \\ 1 \end{pmatrix}.$$

Since both eigenvalues are negative, the equilibrium point is a stable node.

(b) For  $\alpha = 2$ , the characteristic equation is  $\lambda^2 + 2\lambda - 1 = 0$ . Therefore, the eigenvalues are  $\lambda = -1 \pm \sqrt{2}$ . The eigenvector corresponding to  $\lambda_1 = -1 + \sqrt{2}$  is  $\mathbf{v}_1 = (1 \ -\sqrt{2})^T$ . The eigenvector corresponding to  $\lambda_2 = -1 - \sqrt{2}$  is  $\mathbf{v}_2 = (1 \ \sqrt{2})^T$ . Therefore, the general solution is

$$\mathbf{x}(t) = c_1 e^{(-1+\sqrt{2})t} \begin{pmatrix} 1 \\ -\sqrt{2} \end{pmatrix} + c_2 e^{(-1-\sqrt{2})t} \begin{pmatrix} 1 \\ \sqrt{2} \end{pmatrix}.$$

Since the eigenvalues have opposite sign, the equilibrium point is a saddle point.

(c) For general  $\alpha$ , the characteristic equation is  $\lambda^2 + 2\lambda + 1 - \alpha = 0$ . The eigenvalues are given by  $\lambda = -1 \pm \sqrt{\alpha}$ . For  $0.5 \leq \alpha \leq 2$ , both eigenvalues are real and clearly  $-1 - \sqrt{\alpha} < 0$ . Therefore, we just need to determine whether  $-1 + \sqrt{\alpha} = 0$ . We see this occurs when  $\alpha = 1$ . At that value the equilibrium point switches from a saddle point (for  $\alpha > 1$ ) to a stable node (for  $\alpha < 1$ ).